

**Amendments to the Claims:**

This listing of claims will replace all prior versions, and listings, of claims in the application:

**Listing of Claims:**

1. (original) A method for assisting the laser drilling of a hole in a part, comprising the steps of:

providing a camera;

providing a target hole at a first position;

capturing a first image of said target hole at said first position with said camera;

moving said target hole to a second position and capturing a second image of said target hole; and

computing a drilling location of said target hole from said first image and said second image, said computed drilling location used to laser drill said target hole.

2. (original) The method of claim 1 comprising the additional step of calibrating said laser.

3. (original) The method of claim 2 wherein calibrating said laser comprises the steps of:

providing a calibration block having a pinhole;

aligning a laser beam with said pinhole; and

setting a home position of said laser.

4. (original) The method of claim 2 comprising the additional step of calibrating said camera.

5. (original) The method of claim 4 wherein calibrating said camera comprising the steps of:

providing a calibration block;

mounting a calibration target on said calibration block;

imaging said calibration target at a plurality of positions along a z-axis with said camera from said first position and said second position;

computing a 3D-to-2D mapping from said imaged calibration target; and

storing said 3D-to-2D mapping on a storage medium.

6. (original) The method of claim 1 wherein providing said target hole comprises providing a part having at least one said target hole.

7. (original) The method of claim 6 wherein providing said target hole comprises providing a turbine blade having at least one said target hole.

8. (currently amended) The method of claim 1 comprising the additional step of retrieving a nominal position of said target hole from ~~said~~ a storage medium; and moving said target hole to said nominal position.

9. (currently amended) The method of claim 1 wherein computing said drilling location of said target hole comprises using image processing software to locate an actual target hole location, and computing an offset between said actual target hole location and ~~said~~ a nominal position.

10. (currently amended) An apparatus for laser drilling a hole in a part, comprising:

a laser;

a camera mounted to said laser for capturing a first image of a target hole on a part at a first position and a second image of said target hole at a second position; and

means for computing a drilling location of said target hole from said first image and said second image.

11. (original) The apparatus of claim 10 additionally comprising a calibration block having a pinhole for determining a home position of said laser.

12. (original) The apparatus of claim 10 wherein said target hole is located in a turbine blade.

13. (previously presented) The apparatus of claim 10 additionally comprising a means for identifying and extracting a nominal position of said target hole.

14. (currently amended) A vision system, comprising:

a single camera to image a part;

a fixture for said part, said fixture movable between a first position where said camera can capture a first image of said part and a second position where said camera can capture a second image of said part; ~~and~~

means for computing a location of a target on said part from said first image and said second image; and

said system being in combination with a laser drilling apparatus.

15. (cancelled)

16. (currently amended) The vision system of claim ~~15~~ 14, wherein said target is a location of a hole.

17. (original) The vision system of claim 16, wherein said hole is a cooling hole.